

3次元中心差分によるナビエ-ストーク方程式

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1. 基礎方程式

$$\operatorname{div}(v) = 0$$

$$\frac{\partial v}{\partial t} + (v \cdot \nabla)v = -\nabla p + \frac{1}{\operatorname{Re}} \Delta v$$

2. 離散化対象式

下記の速度-圧力法でのナビエ-ストーク方程式を通常格子で離散化する。

(1) $\operatorname{div}, \nabla$ での表示

$$-\Delta p = \operatorname{div}(v \cdot \nabla)v - \operatorname{div}(v) / \Delta t$$

$$\frac{\partial v}{\partial t} + (v \cdot \nabla)v = -\nabla p + \frac{1}{\operatorname{Re}} \Delta v$$

(2) $\operatorname{div}(v \cdot \nabla)v, (v \cdot \nabla)v$ の x, y, z 微分による表示

$$D = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$\begin{aligned} \operatorname{div}(v \cdot \nabla)v &= \frac{\partial}{\partial x} \left(u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) + \frac{\partial}{\partial y} \left(u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) + \frac{\partial}{\partial z} \left(u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right) \\ &= \left(\frac{\partial u}{\partial x} \right)^2 + \frac{\partial v}{\partial x} \cdot \frac{\partial u}{\partial y} + \frac{\partial w}{\partial x} \cdot \frac{\partial u}{\partial z} + \left(\frac{\partial v}{\partial y} \right)^2 + \frac{\partial v}{\partial x} \cdot \frac{\partial v}{\partial y} + \frac{\partial w}{\partial y} \cdot \frac{\partial v}{\partial z} + \left(\frac{\partial w}{\partial z} \right)^2 + \frac{\partial w}{\partial x} \cdot \frac{\partial u}{\partial z} \\ &\quad + \frac{\partial w}{\partial y} \cdot \frac{\partial v}{\partial z} + \frac{\partial D}{\partial x} + \frac{\partial D}{\partial y} + \frac{\partial D}{\partial z} \end{aligned}$$

$$= \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 + 2 \frac{\partial v}{\partial x} \cdot \frac{\partial u}{\partial y} + 2 \frac{\partial w}{\partial y} \cdot \frac{\partial v}{\partial z} + 2 \frac{\partial u}{\partial z} \cdot \frac{\partial w}{\partial x}$$

$$\begin{aligned} (v \cdot \nabla)u &= u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = \frac{\partial}{\partial x} (u^2) + \frac{\partial}{\partial y} (uv) + \frac{\partial}{\partial z} (uw) + u \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \\ &= \frac{\partial}{\partial x} (u^2) + \frac{\partial}{\partial y} (uv) + \frac{\partial}{\partial z} (uw) \end{aligned}$$

$$(v \cdot \nabla)v = u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = \frac{\partial}{\partial x} (uv) + \frac{\partial}{\partial y} (v^2) + \frac{\partial}{\partial z} (vw)$$

$$(v \cdot \nabla)w = u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = \frac{\partial}{\partial x} (uw) + \frac{\partial}{\partial y} (vw) + \frac{\partial}{\partial z} (w^2)$$

(3) 保存形での x, y, z 微分表示

$$\begin{aligned}
 -\frac{\partial^2 p}{\partial x^2} - \frac{\partial^2 p}{\partial y^2} - \frac{\partial^2 p}{\partial z^2} &= \left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial v}{\partial y}\right)^2 + \left(\frac{\partial w}{\partial z}\right)^2 + 2\left(\frac{\partial v}{\partial x} \cdot \frac{\partial u}{\partial y} + \frac{\partial w}{\partial y} \cdot \frac{\partial v}{\partial z} + \frac{\partial u}{\partial z} \cdot \frac{\partial v}{\partial x}\right) \\
 &\quad - \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) / \Delta t \\
 \frac{\partial u}{\partial t} + \frac{\partial(u^2)}{\partial x} + \frac{\partial(uv)}{\partial y} + \frac{\partial(uw)}{\partial z} &= -\frac{\partial p}{\partial x} + \frac{1}{\text{Re}} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) \\
 \frac{\partial v}{\partial t} + \frac{\partial(uv)}{\partial x} + \frac{\partial(v^2)}{\partial y} + \frac{\partial(vw)}{\partial z} &= -\frac{\partial p}{\partial y} + \frac{1}{\text{Re}} \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) \\
 \frac{\partial w}{\partial t} + \frac{\partial(uw)}{\partial x} + \frac{\partial(vw)}{\partial y} + \frac{\partial(w^2)}{\partial z} &= -\frac{\partial p}{\partial z} + \frac{1}{\text{Re}} \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right)
 \end{aligned}$$

(4) 非保存形での x, y, z 微分表示

$$\begin{aligned}
 -\frac{\partial^2 p}{\partial x^2} - \frac{\partial^2 p}{\partial y^2} - \frac{\partial^2 p}{\partial z^2} &= \left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial v}{\partial y}\right)^2 + \left(\frac{\partial w}{\partial z}\right)^2 + 2\left(\frac{\partial v}{\partial x} \cdot \frac{\partial u}{\partial y} + \frac{\partial w}{\partial y} \cdot \frac{\partial v}{\partial z} + \frac{\partial u}{\partial z} \cdot \frac{\partial v}{\partial x}\right) \\
 &\quad - \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) / \Delta t \\
 \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} &= -\frac{\partial p}{\partial x} + \frac{1}{\text{Re}} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) \\
 \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} &= -\frac{\partial p}{\partial y} + \frac{1}{\text{Re}} \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) \\
 \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} &= -\frac{\partial p}{\partial z} + \frac{1}{\text{Re}} \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right)
 \end{aligned}$$

3. 中心差分での離散化計算式

3.1 P の離散化

保存形、非保存形共に下記を使用する。

$$\begin{aligned}
& \frac{2p_{i,j,k} - p_{i-1,j,k} - p_{i+1,j,k}}{(\Delta x)^2} + \frac{2p_{i,j,k} - p_{i,j-1,k} - p_{i,j+1,k}}{(\Delta y)^2} + \frac{2p_{i,j,k} - p_{i,j-1,k} - p_{i,j+1,k}}{(\Delta z)^2} = \\
& \frac{(u_{i+1,j,k} - u_{i-1,j,k})^2}{4(\Delta x)^2} + \frac{(v_{i,j+1,k} - v_{i,j-1,k})^2}{4(\Delta y)^2} + \frac{(v_{i,j,k+1} - v_{i,j,k-1})^2}{4(\Delta z)^2} \\
& + \frac{(v_{i+1,j,k} - v_{i-1,j,k})(u_{i,j+1,k} - u_{i,j-1,k})}{2\Delta x \Delta y} + \frac{(w_{i,j+1,k} - w_{i,j-1,k})(v_{i,j,k+1} - v_{i,j,k-1})}{2\Delta y \Delta z} \\
& + \frac{(u_{i,j,k+1} - u_{i,j,k-1})(w_{i+1,j,k} - w_{i-1,j,k})}{2\Delta z \Delta x} \\
& - \left(\frac{u_{i+1,j,k} - u_{i-1,j,k}}{2\Delta x} + \frac{v_{i,j+1,k} - v_{i,j-1,k}}{2\Delta y} + \frac{w_{i,j,k+1} - w_{i,j,k-1}}{2\Delta z} \right) / \Delta t
\end{aligned}$$

3.2 保存形の離散化

時刻 $(n+1)\Delta t$ の値は $u_{i,j,k}^{(n+1)}$ のように右肩に $(n+1)$ のインデックスを付けて表示

時刻 $n\Delta t$ の値は $u_{i,j,k}$ のように右肩の (n) のインデックスは省いて表示する。

(1) u の離散化

$$\begin{aligned}
\frac{u_{i,j,k}^{(n+1)} - u_{i,j,k}}{\Delta t} &= -\frac{u_{i+1,j,k}^2 - u_{i-1,j,k}^2}{2\Delta x} - \frac{u_{i,j+1,k}v_{i,j+1,k} - u_{i,j-1,k}v_{i,j-1,k}}{2\Delta y} \\
&\quad - \frac{u_{i,j,k+1}w_{i,j,k+1} - u_{i,j,k-1}w_{i,j,k-1}}{2\Delta z} - \frac{p_{i+1,j,k} - p_{i-1,j,k}}{2\Delta x} \\
&+ \left(\frac{u_{i+1,j,k} - 2u_{i,j,k} + u_{i-1,j,k}}{(\Delta x)^2} + \frac{u_{i,j+1,k} - 2u_{i,j,k} + u_{i,j-1,k}}{(\Delta y)^2} + \frac{u_{i,j,k+1} - 2u_{i,j,k} + u_{i,j,k-1}}{(\Delta z)^2} \right) / \text{Re}
\end{aligned}$$

(2) v の離散化

$$\begin{aligned}
\frac{v_{i,j,k}^{(n+1)} - v_{i,j,k}}{\Delta t} &= -\frac{u_{i+1,j,k}v_{i+1,j,k} - u_{i-1,j,k}v_{i-1,j,k}}{2\Delta x} - \frac{v_{i,j+1,k}^2 - v_{i,j-1,k}^2}{2\Delta y} \\
&\quad - \frac{v_{i,j,k+1}w_{i,j,k+1} - v_{i,j,k-1}w_{i,j,k-1}}{2\Delta z} - \frac{p_{i,j+1,k} - p_{i,j-1,k}}{2\Delta y} \\
&+ \left(\frac{v_{i+1,j,k} - 2v_{i,j,k} + v_{i-1,j,k}}{(\Delta x)^2} + \frac{v_{i,j+1,k} - 2v_{i,j,k} + v_{i,j-1,k}}{(\Delta y)^2} + \frac{v_{i,j,k+1} - 2v_{i,j,k} + v_{i,j,k-1}}{(\Delta z)^2} \right) / \text{Re}
\end{aligned}$$

(3) w の離散化

$$\begin{aligned} \frac{w_{i,j,k}^{(n+1)} - w_{i,j,k}}{\Delta t} = & -\frac{u_{i+1,j,k} w_{i+1,j,k} - u_{i-1,j,k} w_{i-1,j,k}}{2\Delta x} - \frac{v_{i,j+1,k} w_{i,j+1,k} - v_{i,j-1,k} w_{i,j-1,k}}{2\Delta y} \\ & - \frac{w_{i,j,k+1}^2 - v_{i,j,k-1}^2}{2\Delta z} - \frac{p_{i,j,k+1} - p_{i,j,k-1}}{2\Delta z} \\ & + \left(\frac{v_{i+1,j,k} - 2v_{i,j,k} + v_{i-1,j,k}}{(\Delta x)^2} + \frac{v_{i,j+1,k} - 2v_{i,j,k} + v_{i,j-1,k}}{(\Delta y)^2} + \frac{v_{i,j,k+1} - 2v_{i,j,k} + v_{i,j,k-1}}{(\Delta z)^2} \right) / \text{Re} \end{aligned}$$

3.3 非保存形の離散化

(1) u の離散化

$$\begin{aligned} \frac{u_{i,j,k}^{(n+1)} - u_{i,j,k}}{\Delta t} = & -u_{i,j,k} \cdot \frac{u_{i+1,j,k} - u_{i-1,j,k}}{2\Delta x} - v_{i,j,k} \cdot \frac{u_{i,j+1,k} - u_{i,j-1,k}}{2\Delta y} \\ & - w_{i,j,k} \cdot \frac{u_{i,j,k+1} - u_{i,j,k-1}}{2\Delta z} - \frac{p_{i+1,j,k} - p_{i-1,j,k}}{2\Delta x} \\ & + \left(\frac{u_{i+1,j,k} - 2u_{i,j,k} + u_{i-1,j,k}}{(\Delta x)^2} + \frac{u_{i,j+1,k} - 2u_{i,j,k} + u_{i,j-1,k}}{(\Delta y)^2} + \frac{u_{i,j,k+1} - 2u_{i,j,k} + u_{i,j,k-1}}{(\Delta z)^2} \right) / \text{Re} \end{aligned}$$

(2) v の離散化

$$\begin{aligned} \frac{v_{i,j,k}^{(n+1)} - v_{i,j,k}}{\Delta t} = & -u_{i,j,k} \cdot \frac{v_{i+1,j,k} - v_{i-1,j,k}}{2\Delta x} - v_{i,j,k} \cdot \frac{v_{i,j+1,k} - v_{i,j-1,k}}{2\Delta y} \\ & - w_{i,j,k} \cdot \frac{v_{i,j,k+1} - v_{i,j,k-1}}{2\Delta z} - \frac{p_{i,j+1,k} - p_{i,j-1,k}}{2\Delta y} \\ & + \left(\frac{v_{i+1,j,k} - 2v_{i,j,k} + v_{i-1,j,k}}{(\Delta x)^2} + \frac{v_{i,j+1,k} - 2v_{i,j,k} + v_{i,j-1,k}}{(\Delta y)^2} + \frac{v_{i,j,k+1} - 2v_{i,j,k} + v_{i,j,k-1}}{(\Delta z)^2} \right) / \text{Re} \end{aligned}$$

(3) w の離散化

$$\begin{aligned} \frac{w_{i,j,k}^{(n+1)} - w_{i,j,k}}{\Delta t} = & -u_{i,j,k} \cdot \frac{w_{i+1,j,k} - w_{i-1,j,k}}{2\Delta x} - v_{i,j,k} \cdot \frac{w_{i,j+1,k} - w_{i,j-1,k}}{2\Delta y} \\ & - w_{i,j,k} \cdot \frac{w_{i,j,k+1} - w_{i,j,k-1}}{2\Delta z} - \frac{p_{i,j,k+1} - p_{i,j,k-1}}{2\Delta z} \\ & + \left(\frac{w_{i+1,j,k} - 2w_{i,j,k} + w_{i-1,j,k}}{(\Delta x)^2} + \frac{w_{i,j+1,k} - 2w_{i,j,k} + w_{i,j-1,k}}{(\Delta y)^2} + \frac{w_{i,j,k+1} - 2w_{i,j,k} + w_{i,j,k-1}}{(\Delta z)^2} \right) / \text{Re} \end{aligned}$$